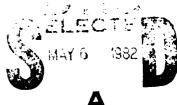


S. M. Coulter and E. J. Marquart Calspan Field Services, Inc.

February 1981

Final Report for Period December 8, 1980 - February 26, 1981

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NOMENCLATURE

AD	Rate of change of angle at attack, rad/sec
ALPHA	Model angle of attack, deg
В	Wing span, 1.65 ft
BD	Rate of change of angle of sideslip, rad/sec
BETA	Sideslip angle in the stability axis system, deg
CBAR	Wing mean aerodynamic chord, 0.62233 ft
CLL	M _Q /(Q·S·B)
CLL-A	∂CLL/∂ALPHA, rad ⁻¹
CLL-AD	$\partial CLL/\partial (Q \cdot CBAR/2V) + \partial CLL/\partial (AD \cdot CBAR/2V)$, rad ⁻¹
CLL-B	[acll/abeta] cos Alpha for yaw test phase (measured by can balance) or
	[acll/abeta] sin AlPHA for roll test phase, rad-1
CLL-BD	∂CLL/∂(RB/2V)-[∂CLL/∂(BD•B/2V)] cos ALPHA, rad ⁻¹
CLL-PBD	$\partial CLL/\partial (P \cdot B/2V) + [\partial CLL/\partial (BD \cdot B/2V)] \sin ALPHA, rad^{-1}$
CLM	$M_{\rm m}/Q \cdot S \cdot CBAR$
CLM-A	aclm/aalpha, measured by can balance, rad-1
CLM-AD	$\partial CLM/\partial (Q \cdot CBAR/2V) + \partial CLM/\partial (AD \cdot CBAR/2V)$, measured by can balance, rad ⁻¹
CLM-B	[aclm/abeta] cos Alpha, rad-1
CLM-BD	$\partial CLM/\partial (R \cdot B/2V) - [\partial CLM/\partial (BD \cdot B/2V)] \cos ALPHA, rad^{-1}$
CLN	$M_n/Q \cdot S \cdot B$
CLN-A	∂CLN/∂ALPHA, rad ⁻¹
CLN-AD	$\partial CLN/\partial (Q \cdot CBAR/2V) + \partial CLN/\partial (AD \cdot CBAR/2V), rad^{-1}$
CLN-B	[acln/abeta] cos Alpha, measured by can balance, rad ⁻¹

CLN-BD	$\partial CLN/\partial (R \cdot B/2V) - [\partial CLN/\partial (BD \cdot B/2V)] \cos ALPHA,$ measured by can balance, rad ⁻¹
CLN-PBD	$\partial CLN/\partial (P \cdot B/2V) + [\partial CLN/\partial (BD \cdot B/2V)] \sin ALPHA, rad^{-1}$
CN	F _N /Q·S
CN-A	∂CN/∂ALPHA, rad ⁻¹
CN-AD	$\partial CN/\partial (Q \cdot CBAR/2V) + \partial CN/\partial (AD \cdot CBAR/2V)$, rad ⁻¹
CY.	F _Y /Q·s
СҮ-В	[acy/abeta] cos Alpha
CY-BD	∂CY/∂(R•B/2V) - [∂CY/∂(BD•B/2V)] cos ALPHA, rad ⁻¹
CYPBD	<pre>∂CY/∂(P•B/2V) + [∂CY/∂(BD•B/2V] sin ALPHA, rad⁻¹</pre>
CONFIG	Model configuration
E	Amplitude of excitation voltage, volts
F.S.	Fuselage Station, inches
F _N	Normal force, 1b
F _Y	Side force, 1b
м	Free-stream Mach number
M _{&}	Rolling moment, ft-lb
M m	Pitching moment, ft-lb
M _n	. Yawing moment, ft-lb
MAC	Model mean aerodynamic chord, 0.62233 ft
MOF	Balance restoring spring constant, in-lb/deg
NCP	Center of pressure location, in the normal plane, expressed in terms of the model reference length from the model moment reference point

OMEGA	Wind-on angular frequency, rad/sec
P	Free-stream static pressure, psfa or
	rolling velocity, rad/sec
POC	Program option code, Pitch = 1
	Yaw = 5 Roll = 8
Pos	Model oscillation amplitude, deg
PT	Tunnel stilling chamber pressure, psfa
P/Y CLM	M _m /Q·S·CBAR, measured by pitch/yaw balance
P/Y CLM-A	aclm/aalpha, measured by pitch/yaw balance,
	rad ⁻¹
P/Y CLM-AD	<pre>∂CLM/∂(Q•CBAR/2V) + ∂CLM/∂(AD•CBAR/2V), measured</pre>
	by pitch/yaw balance, rad ⁻¹
P/Y CLN	$M_n/Q \cdot S \cdot B$, measured by pitch/yaw balance
P/Y CLN-B	[acln/abeta] cos Alpha, measured by pitch/yaw
	balance, rad ⁻¹
P/Y CLN-BD	∂CLN/∂(R•B/2V) - [∂CLN/∂(BD•B/2V)] cos ALPHA,
	measured by pitch/yaw balance, rad ⁻¹
Q	Free-stream dynamic pressure, psfa or
	pitching velocity, rad/sec
R	Yawing velocity, rad/sec
RE	Free-stream Reynolds number, ft ⁻¹
RFP	Reduced frequency parameter (OMEGA·CBAR/2V) for pitch phase, (OMEGA·B/2V) for yaw and roll phases
s	Reference model wing area, 0.907 ft ²
TP	Data point number
TT	Tunnel stilling chamber temperature, degrees F or R

W.L.	Water line, inches
v	Free stream velocity, ft/sec
YCP	Center of pressure location, in the side plane, in terms of the model reference length from the model moment reference point
$\phi_{\mathbf{B}}$	Roll angle of balance-sting assembly; ϕ_B = 90 deg for yaw oscillation of balance
θ	Total deflection of cross-flexure, deg
$\overline{m{ heta}}_{\mathbf{T}}$	Static deflection of cross-flexure, deg

1.0 INTRODUCTION

The work reported herein was sponsored by the Arnold Engineering Development Center (AEDC), Air Force Systems Command (AFSC), Arnold Air Force Station, Tennessee, under Program Element 65807F, and Control Number 9T02. The results were obtained by Calspan Field Services, Inc./AEDC Division, operating contractor for the Aerospace Flight Dynamics testing effort at the AEDC, AFSC, Arnold Air Force Station, Tennessee. The tests were conducted in the Propulsion Wind Tunnel Facility (PWT) Aerodynamic Wind Tunnel (4T) under AEDC Project Number C005-PB, December 8 through December 13, 1980. This test was a subtask of the 4T Facility Improvement Program. The project sponsor was Major R. L. Bruce, DOFA, AEDC.

This test was part of a continuing effort to design, fabricate, and verify the performance of forced oscillation dynamic balance systems capable of measuring direct, cross, and cross-coupling derivatives at high angles of attack. The 1,500-lb (normal force) Pitch/Yaw and Roll balance systems were utilized. The objectives of the test were to:

- (1) verify the controllability of the oscillating model over the operating range of the tunnel,
- (2) verify the quantitative measurements of the balance systems by comparing to previous data, and
- (3) further investigate the capabilities and problems associated with measuring cross and cross-coupling derivatives.

Forced oscillation data about the pitch, yaw, and roll axis were obtained on the Standard Dynamics Model (SDM) at angles of attack of -4 to 24 deg at Mach numbers 0.3 to 1.3. The unit Reynolds number ranged from 1.0 x 10^6 to 2.5 x 10^5 . The reduced frequency parameter varied from 0.012 to 0.04 for pitch oscillation, from 0.017 to 0.058 for yaw oscillation, and from 0.034 to 0.13 for roll oscillation. The nominal frequencies were 7.35 Hz, 3.65 Hz, and 8.5 Hz for pitch, yaw, and roll, respectively. The model was oscillated at amplitudes of 0.5, 1.0, and 1.5 deg.

A microfilm copy of the final data has been retained in the PWT at AEDC. Inquiries to obtain copies of the test data should be addressed to AEDC/DOS, Arnold Air Force Station, Tennessee 37389.

2.0 APPARATUS

2.1 TEST FACILITY

The Aerodynamic Wind Tunnel (4T) is a closed-loop, continuous flow, variable-density tunnel in which the Mach number can be varied from 0.1 to 1.3 and can be set at discrete Mach numbers of 1.6 and 2.0 by placing nozzle inserts over the permanent sonic nozzle. At all Mach numbers, the

stagnation pressure can be varied from 400 to 3,400 psfa. The test section is 4-ft square and 12.5 ft long with perforated, variable porosity (0.5- to 10-percent open) walls. It is completely enclosed in a plenum chamber from which the air can be evacuated, allowing part of the tunnel airflow to be removed through the perforated walls of the test section. The model support system consists of a sector and boom attachment which has a pitch angle capability of -5 to 24 deg with respect to the tunnel centerline. Guy rod stiffeners were used to strengthen the boom in the yaw plane. The general arrangement of the test section with the test article installed is shown in Fig. 1. A more complete description of the tunnel may be found in Ref. 1.

2.2 TEST ARTICLE

The Standard Dynamics Model (SDM) represents a 1/18-scale fighter type aircraft. Dimensions of the SDM are shown in Fig. 2, and details are shown in Fig. 3. The model has a 19.8 in. wing span and double-taper leading and trailing edges on the wing, stabilators, and vertical tail. The stabilators may be deflected in increments of ±5 deg. For this test, the stabilator was deflected -5 deg. All external components, that is wings, stabilators, inlet, ventral fins, canopy, etc., may be removed for buildup tests as desired. Table 1 lists the Configuration codes for the test reported herein. The balance pivot center, model center, model center of gravity, and model moment reference point were located at 35 percent MAC. The two configurations tested were (see Table 1)

-B1C1W1V1T05S1F1I1 - full symmetrical aircraft

-B1C1W1V1T05S0F1I1 - full aircraft with left-hand (looking upstream) forebody strake removed.

The heavy wing tips (W2) were installed for the roll phase.

2.3 TEST MECHANISH

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The pitch/yaw balance and its external 5-component can balance are shown in Figs. 4 and 5, respectively. A photograph of this arrangement is shown in Fig. 6. For the roll case, the cross-derivative balance was designed as an integral part of the balance system as shown in Fig. 7. These systems were designed, fabricated, and bench checked under various technology and development programs at AEDC.

The P/Y and roll balances use the same principle of operation and control. Each balance consists of a cross-flexure pivot connected to a hydraulic cylinder through a force measuring flexure. The hydraulic cylinder is operated with a servo valve to obtain sinusoidal oscillation motion at a constant oscillation amplitude, up to ±2 deg, and constant frequency from 2 to about 10 Hz. The cross flexure is instrumented to measure angular displacement and supports the model loads (up to 1,500 lb normal force and 600 lb axial force) and provides the restoring moment to cancel the inertia moment when the system is operating at the natural frequency of the model/balance assembly. The P/Y balance has provisions for changing the restoring moment by installing leaf springs on the sides of the balance; leaf springs were used for these tests. The restoring moment was 348 in-1b/deg for the P/Y balance and 43 in-1b/deg for the roll balance. The P/Y balance was oriented at 0 deg with respect to the model for the pitch tests and at 90 deg for the yaw tests.

The can balance and its load limits are shown in Fig. 5. The balance has five components of load measuring elements: pitching moment and normal force, yawing moment and side force, and rolling moment. Each element is instrumented to resolve the static, in-phase, and out-of-phase (with respect to the model position vector) component of the load as discussed later. The balance is capable, therefore, of measuring the same derivatives as the pitch-yaw balance, as well as the cross and cross-coupling derivatives.

2.4 TEST INSTRUMENTATION

The Forced Oscillation Balance Control and Readout System (FOBCARS) is used for setting the oscillation frequency and amplitude and for nulling the static torque. An electronic position feedback loop is used to maintain a constant oscillation amplitude and frequency under aerodynamic loads and permits testing both dynamically stable and unstable configurations. Data are normally obtained at the natural frequency of the model/flexure spring-mass system. Limit circuits are set prior to the test to provide overload protection for the balance. These limit circuits automatically shut the system down when they are exceeded. The torque-nulling system centers the hydraulic-driven piston so the force-measuring flexure (termed "torque beam") is not subjected to the model static aerodynamic moment. This allows the use of a torque beam suitable to the particular model for increased sensitivity.

Each load measuring element of each balance is instrumented with three sets of strain gages. Two sets of these strain gages are used with the system for each dynamic measurement. A two-phase oscillator provides E sinut (AC) excitation to one set of strain gages to resolve the in-phase (with respect to a reference signal) component of the dynamic signal while E coswt (AC) excitation is used to excite the second set of strain gages to resolve the out-of-phase (quadrature) component (where ω is the oscillation rate of the model). The third set of gages is DC excited to provide readings of static deflections, forces, and moments. A LSI-11 minicomputer and filter-amplifier chassis are used to provide analog-to-digital conversion and signal conditioning. The gage signals first pass through a 2-Hz passive filter, then through a 0.2-Hz active filter. A digital filter routine is performed in the minicomputer. The digital filter parameters can be changed easily depending on the noise of the data. The 32 channels of data are then sent to the facility computer for online data reduction.

3.0 TEST DESCRIPTION

3.1 TEST CONDITIONS AND PROCEDURES

3.1.1 General

A summary of the nominal test conditions at each Mach number is listed below.

<u>M</u>	PT, psf	TT, °F	Q, psf	P, psf	$\frac{\text{RE} \times 10^{-6}}{}$	V ft/sec
0.3 `	2,870	105	170	2,700	2.5	350
0.6	1,480	68	290	1,160	2.5	655
0.6	585	63	115	460	1.0	650
0.95	1,160	70	410	650	2.5	985
0.95	800	65	280	450	1.7	980
1.05	1,130	67	435	560	2.5	1,071
1.05	890	63	341	445	2.0	1,065
1.3	1,100	67	475	400	2.5	1,265

Definition of the configuration code is given in Table 1. The Test Summary is given in Table 2.

3.1.2 Data Acquisition

After establishing tunnel conditions and model attitude, the model was unlocked and brought to a constant oscillation amplitude by using the FOBCARS. The system was allowed to stabilize at the system resonant frequency before data were recorded. At each angle of attack, generally 3 data points were taken.

3.2 DATA REDUCTION

The second section and second second

The digital readouts of the data acquisition instrumentation from the FOBCARS were input to the facility computer for reducing the data to coefficients. The direct damping coefficients were obtained using data reduction equations and procedures given in Ref. 2. The pitch and yaw damping results were corrected for sting motion, as discussed in Ref. 3. The cross and cross-coupling data were reduced using equations derived by methods as discussed in Ref. 4.

3.3 UNCERTAINTY OF MEASUREMENTS

In general, instrumentation calibrations and data uncertainty estimates were made using methods recognized by the National Bureau of Standards (NBS) (Ref. 5). Measurement uncertainty is a combination of bias and precision errors defined as:

$$U = \pm (B + t_{q5}S)$$

where B is the bias limit, S is the sample standard deviation, and t95 is the 95th percentile point for the two-tailed Student's "t" distribution, which for degrees of freedom greater than 30 equals 2.

Estimates of the measured data uncertainties for this test are given in Table 3a, b, and c. The balance data uncertainties were determined from in-place static and dynamic calibrations through the data recording system and data reduction program. Static load hangings on the balances simulate the range of loads and center-of-pressure locations anticipated during the test, and measurement errors are based on differences between applied loads and corresponding values calculated from the balance

equations used in the data reduction. Load hangings to verify the balance calibrations are made in-place on the assembled model. Static and dynamic calibrations of the dynamic stability balance system allowed the measurement uncertainty to be that which is due to the amount of nonrepeatability of the calibration constants. The sting and parts of the balance not dynamically calibrated were calibrated by static load hangings over the range of anticipated loads. Uncertainties in the measurements of sting effects were included in the error analysis. Structural damping values were obtained near vacuum conditions before the tunnel flow was started to evaluate the still-air damping contribution.

Propagation of the bias and precision errors of measured data through the calculated data was made in accordance with Ref. 5, and the results are given in Table 3d. The uncertainties are for steady-state conditions. Occasionally vibration and noise of the wind tunnal environment caused the scatter in the data to exceed the estimated uncertainty.

4.0 DATA PACKAGE PRESENTATION

The Data Package includes tabulated data, plotted data, and a test summary. Tabulated data includes summary data, point-by-point data, wind-off tare data, zeros data, a listing of constants, and miscellanous data, such as check loads, etc. Plotted data includes all static, direct dynamic, cross and cross-coupling data as a function of angle of attack, and comparison plots which depict configuration effects. A sample of the tabulated and plotted data is presented in Appendix 3. The data package is comprised of seven volumes, arranged as follows:

Volume No.	Run Nos.	Description
1 2 3 4 5 6 7	22-61 76-94 113-124 22-61 76-94 113-124	Pitch phase summary and plotted data Yaw phase summary and plotted data Roll phase summary and plotted data Pitch phase point-by-point data Yaw phase point-by-point data Roll phase point-by-point data Zeros, tares, constants, miscellanous

Plots of some of the coefficient data are shown in Fig. 8. The direct derivatives, P/Y CLM-A, P/Y CLM-AD, P/Y CLN-B, P/Y CLN-BD and P/Y CLM compared favorably with previous SDM data (Refs. 6 and 7).

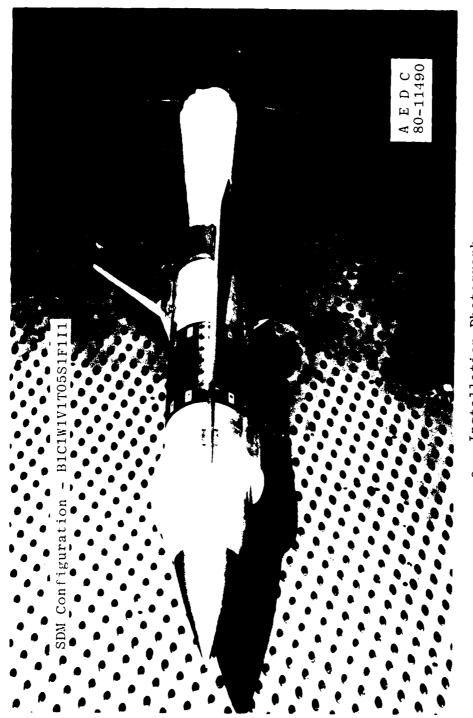
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- 6. Cyran, F.B. "An Investigation of Sting Interference Effects on the Static, Dynamic, and Base Pressure Meaurements of the SDM Aircraft at Mach Numbers 0.3 through 1.3." AEDC-TR-81-3 (AD-A102612), August 1981.
- 7. Cyran, F. B. "An Investigation of Sting Interference Effects on the Static, Dynamic, and Base Pressure Measurements of the SDM Aircraft at Mach Numbers 0.3 through 1.3." AEDC-TR-81-3 (AD-A102612), August 1981.

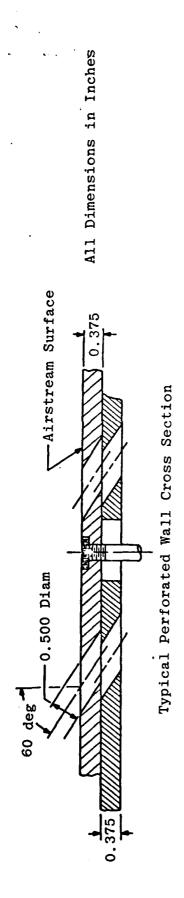
APPENDIX I

ILLUSTRATIONS

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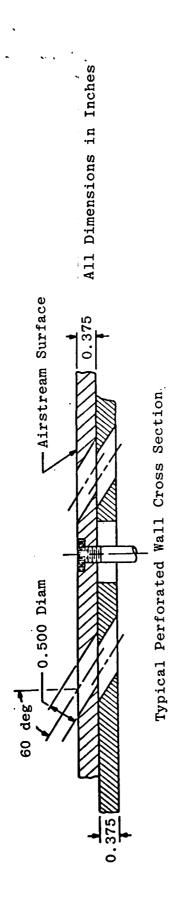
a. Installation Photograph Fig. 1. General Installation Arangement



The state of the s

-Perforated Walls (10-percent Maximum Open Area) Sta. **6** 159.6 Sta. 150.0 Center of Pitch Rotation -46.27-·Pivot Axis -2.0 Sta. 108 Sta. 83.5 65,6 Sta. Solid Areas Sta. 36.0 Flow -Expansion-Sta. 0.0

b. Installation Sketch - Pitch/Yaw Balance Fig. 1. Continued



-Perforated Walls (10-percent Maximum Open Area) Sta. 159.6 2.00 Sta. 150.0 Sting Diam = Center of Pitch Rotation ·Pivot Axis <u>+</u>30 + 108 Sta. Sta. 103 Sta. 85.1 -Solid Areas Sta. 36.0 Flow Expansion -Sta. 0.0

c. Installation Sketch - Roll Balance Fig. 1. Concluded

Schematic of 4T

```
WING
                                    0.90702 ft<sup>2</sup>
   Area
                                    1.6500 ft
   Span
   MAC
                                    0.62233 ft
   Aspect Ratio
                                    3.0
   L.E. Sweep
                                    40 deg
   Dihedral
   Incidence
                            Double Wedge 4.5 percent thickness at root.
   Airfoil
                                   15 (half angle)
15 (half angle)
        L.E. Angle
        T.E. Angle
HORIZONTAL TAIL
                                    0.30707 ft<sup>2</sup>
   Area
   Aspect Ratio
                                    3.0
   Taper Ratio
                                    0.213
   L.E. Sweep
                                    40 deg
   Dihedral
                                    -10 deg
                            Double Wedge 6.4 percent thickness at root.
   Airfoil
                                    14 deg (half angle)
15 deg (half angle)
        L.E. Angle
         T.E. Angle
VERTICAL TAIL
                                   0.30846 ft<sup>2</sup>
   Area
   Aspect Ratio
                                   1.093
   Taper Ratio
                                    0.362
   L.E. Sweep
                                    47.5 deg
         Tip
         Root
                                    15.0 deg
                            Double Wedge 5.6 percent thickness at root.
   Airfoil
        L.E. Angle
                                   15 deg (half angle)
15 deg (half angle)
        T.E. Angle
VENTRAL FIN (Each)
                                   0.0263 ft<sup>2</sup>
   Area
                                    0.150 ft
   Span
                                   0.86
   Aspect Ratio
   Taper Ratio
                                   0.70
   L.E. Sweep
                                   26.5 deg
                                   25.2 deg (outboard)
   Dihedral (cant)
   Airfoil
                           Modified Wedge 3.8 percent thick at root.
        At Root
                                   Constant 0.003 r
        At Tip
FUSELAGE
                                   2.55208 ft
   Length
                                   0.36458 ft
   Diameter
                                   1.49125 ft from Nose @ 35% MAC
   Center of Gravity
                                   1.36667 ft from Nose @ 15% MAC
```

Fig. 2. Standard Dynamics Model (SDM) Dimensions

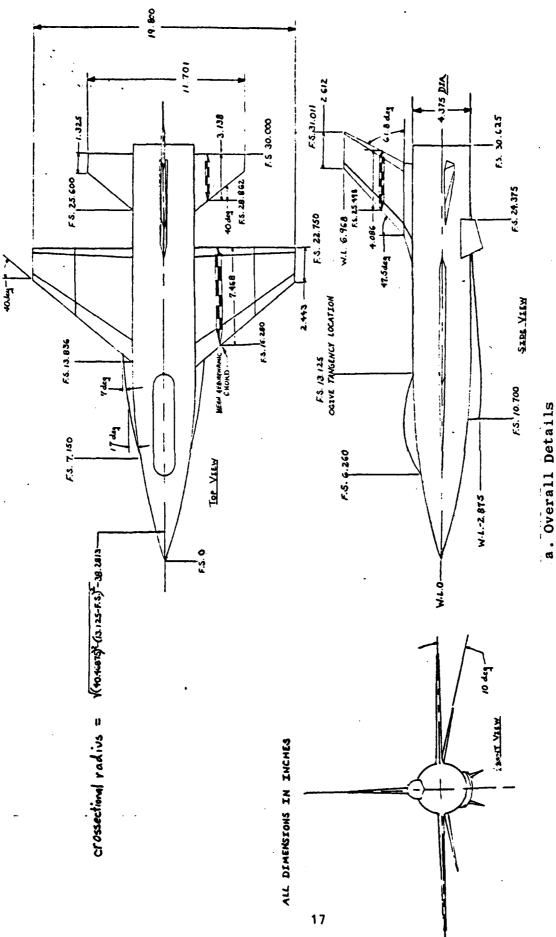
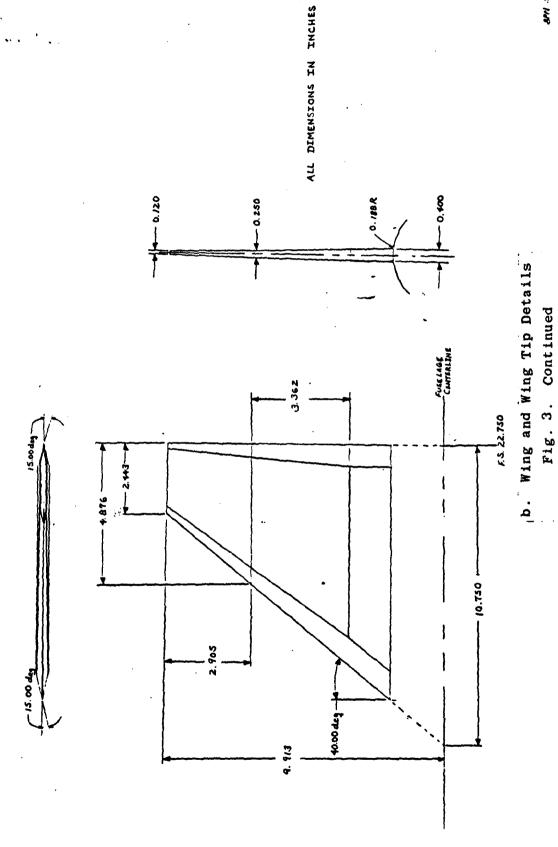
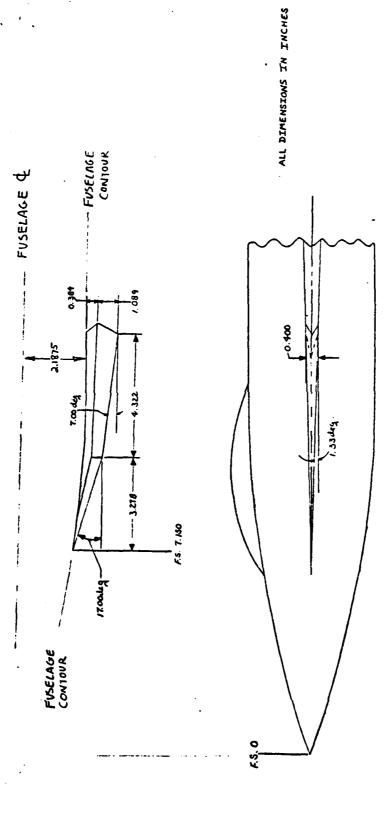
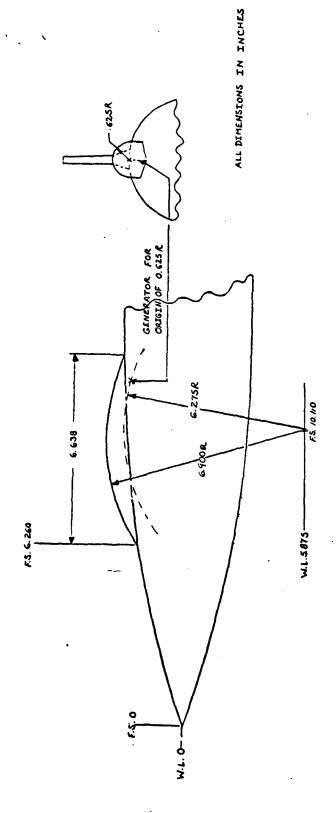


Fig. 3. Standard Dynamics Model (SDM) Details



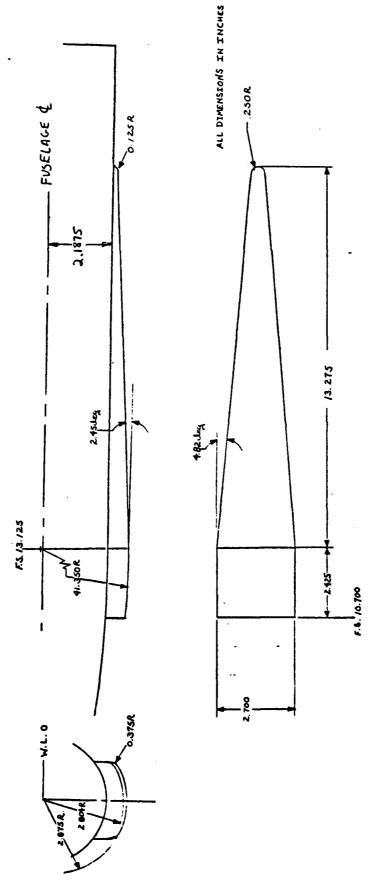


c. Strake Details Fig. 3. Continued



d. Canopy Details Fig. 3. Continued

e. Inlet Details Fig. 3. Continued

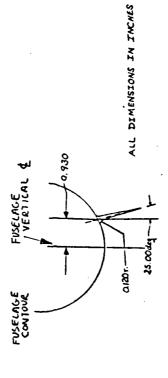


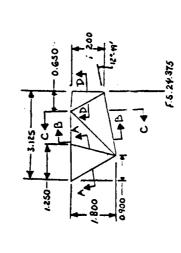
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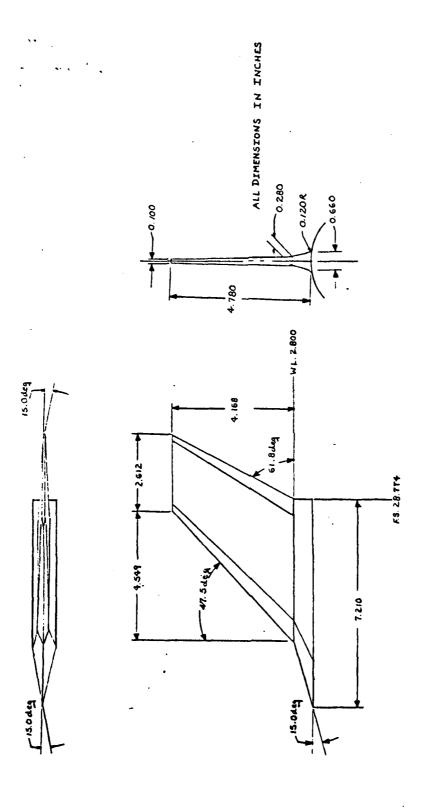


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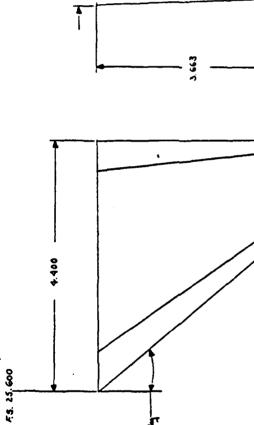
f. Ventral Fin Details Fig. 3. Continued

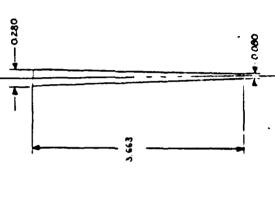


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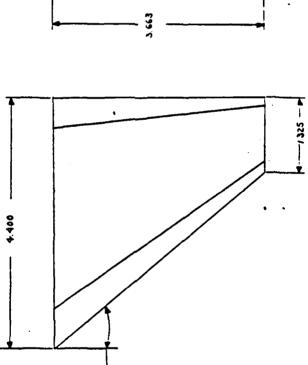
g. Vertical Stabilizer Details Fig. 3. Continued





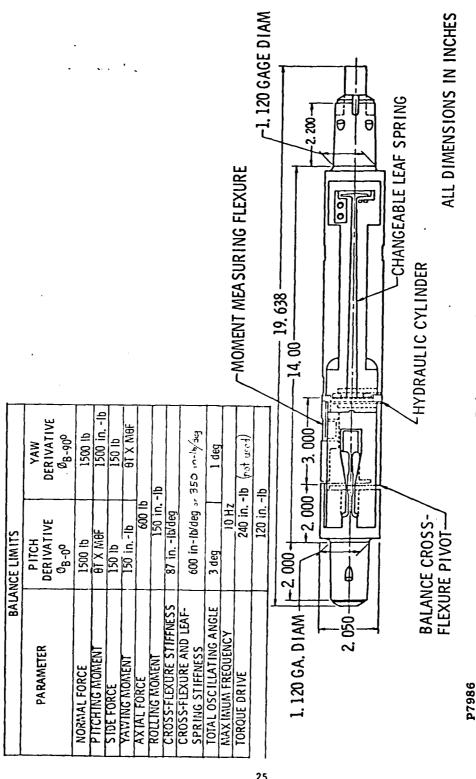


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h. Horizontal Stabilizer Details, Fig. 3. Concluded

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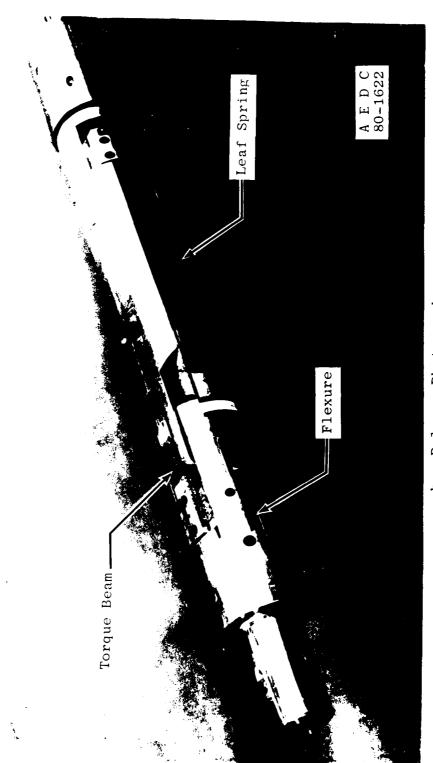


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a. Balance Details

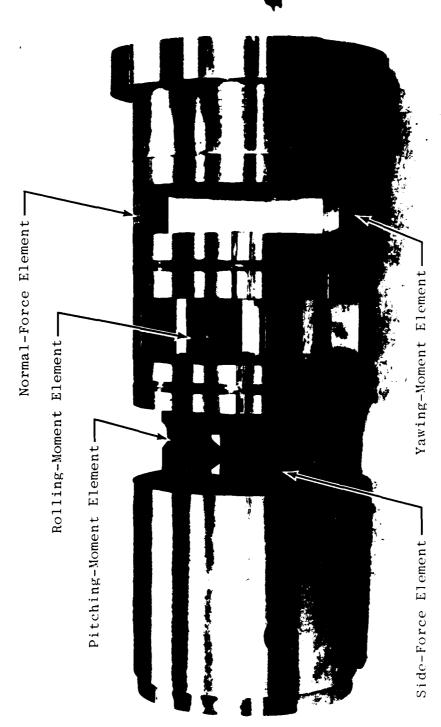


b. Balance PhotographFigure 4. Concluded

	LOAD	BALANCE LIMITS
	F N	1500 LB
	: ≽	150 LB
ς.	M	1050 INLB
	M	525 INLB
	M	150 INLB

a. Balance Details

Figure 5. 1500 lb 5-Component Can Balance



A E D C 80-1623

b. Balance PhotographFigure 5. Concluded

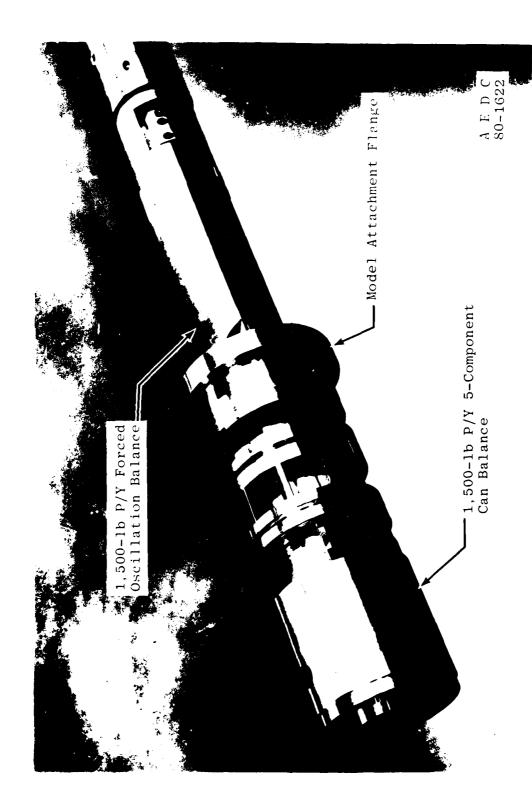
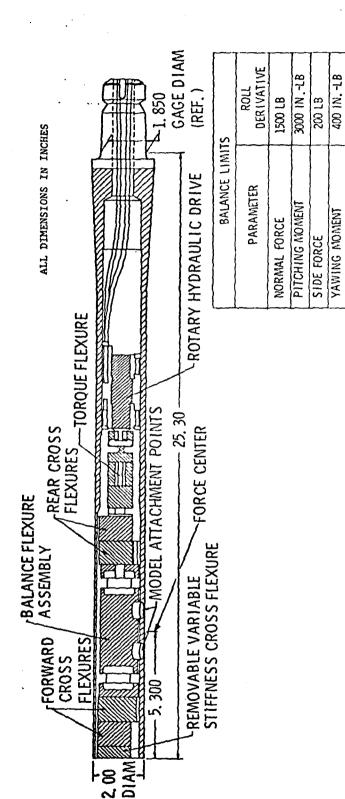


Figure 6. Pitch/Yaw - Can Balance Assembly



30

Figure 7. 1500 lb Roll Dynamic Balance Details

62 IN -LB/DEG

±3 DEG

TOTAL OSCILLATING ANGLE

MAXIMUM FREQUENCY

TORQUE DRIVE

VAR IABLE AND CROSS-FLEXURE STIFFNESS 60 IN. -LB

8 - 10SCILLATION AMPLITUDE)

2H 01

43 IN. -LB/DEG

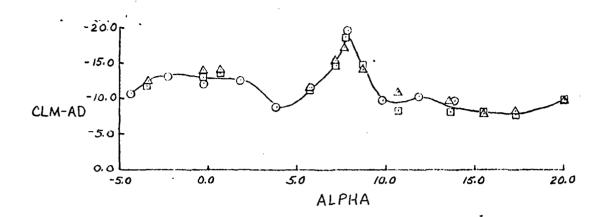
CROSS-FLEXURE STIFFNESS

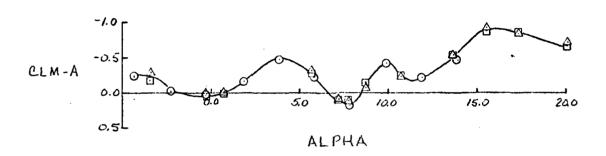
ROLLING MOMENT

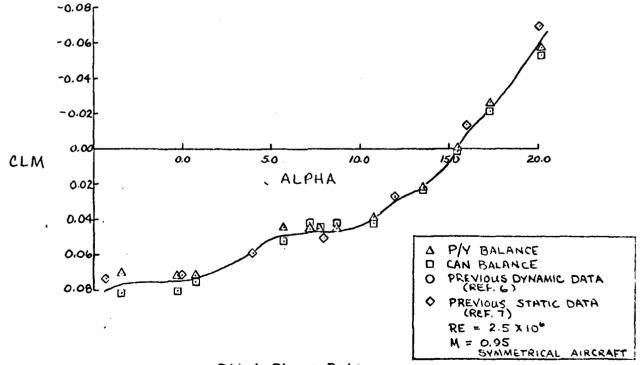
AXIAL FORCE

8 x MBF

600 LB







a. Pitch Phase Data Figure 8. Data Comparisons

CLN-BD

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CLN-BD

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0 PREVIOUS DYNAMIC DATA (REF.7)

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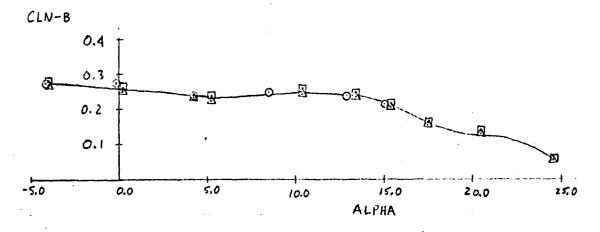
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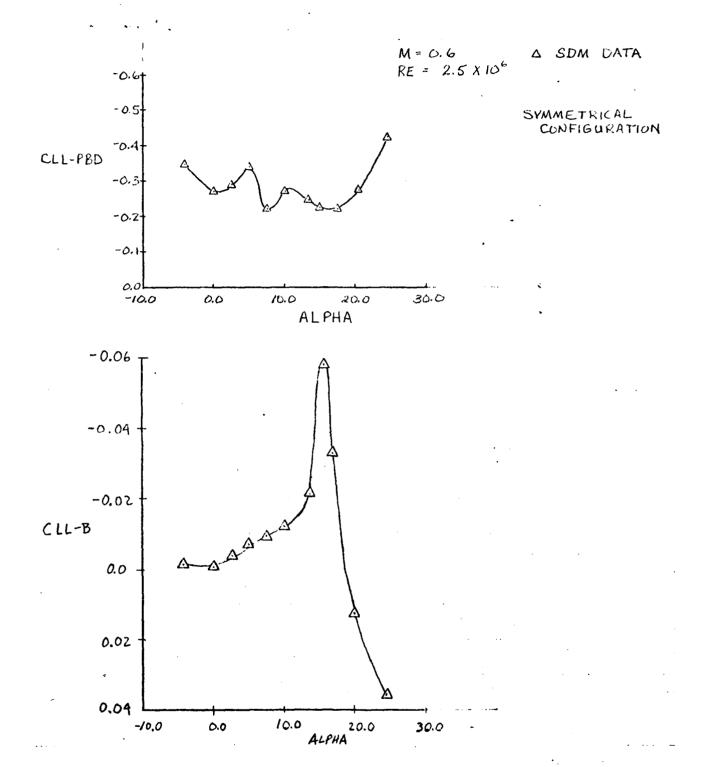
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ALPHA



b. Yaw Phase DataFigure 8. Continued



c. Roll Phase DataFigure 8. Concluded

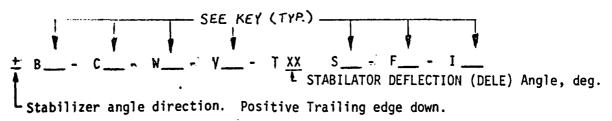
APPENDIX II

TABLES

Table 1

STANDARD DYNAMICS MODEL CONFIGURATION DESIGNATIONS

EXAMPLE	CONFIGURATION DETAIL
B1COWOVOT99	BASIC FUSELAGE BODY (CG at 35% MAC)
B1C1WOVOT99	BODY + CANOPY
B1C1W1V0T99	BODY + CANOPY + WINGS .
B1C2W1V1T99	BODY + CANOPY + WINGS + VERTICAL TAIL
±B1C1W1Y1TXX	BODY + CANOPY + WINGS + VERTICAL TAIL + HORIZONTAL STABILIZERS
±B1C1W1V1TXXS1	BODY + CANOPY + WINGS + VERTICAL TAIL + HORIZONTAL STABILIZERS + STRAKES
±B1C1W1V1TXXS1F1	BODY + CANOPY + WINGS + VERTICAL TAIL + HORIZONTAL STABILIZERS + STRAKES + VENTRAL FINS
±B1C1W1V1TXXS1F1I1	BODY + CANOPY + WINGS + VERTICAL TAIL + HORIZONTAL STABILIZERS + STRAKES + VENTRAL FINS + INLET
±B1C1W1Y1TXXSOF1I1	BODY + CANOPY + WINGS + YERTICAL TAIL + HORIZONTAL STABILIZER + VENTRAL FINS + INLET (NO STRAKES)



NON-ZERO INDICATES COMPONENT ON EXCEPT FOR TAIL WHERE 99 WILL SIGNIFY TAIL OFF

Table 1.-Continued

Standard Configuration Key

KEY		MODEL PART
1	В	BASIC FUSELAGE BODY CG @ 35% MAC
2	В	BASIC FUSELAGE BODY CG @ 15% MAC
1	С	CANOPY
1	W	WINGS - LIGHT TIPS
2	W	- HEAVY TIPS
1	٧	VERTICAL TAIL
±XX deg	Ť	HORIZONTAL STABILIZERS - DEFLECTION 99 signifies tail off
1	S	STRAKES
1	F	VENTRAL FINS
1	I	INLET

TABLE 2. Test Summary

			REX				ALPHA	TEST
RUN	CONFIGURATION	M	106	PT	POS	RFP	RANGE	PHASE
22 23 28 29 30	-B1C1W1V1T05S1F1I1	0.3	2.5	2900	0.5,1.0,1.5 1.5 1.0,1.5	.04	0 10 0 10 20	Pitch
31 32 34 35 36 37		0.95		1160	1.0	.014	0 0 17-20 15 13 10 5	
39 40			*	•		+	-4 -1	
41 45 *46		1.3 0.95	1.75 2.5	800 1110 1160	1 0	.015 .012 .014	20-24 -4-20 6.5-8	
47 48 54 55	-B1ClWlVlT05S0FlI1	0.6 1.05 0.6 0.6	1.0	1480 1130 1480 585	0.5,1.0	.021 .013 .021 .022	-4-24 -4-24 -4-13 0-20	
56 57 60 61		0.95 1.05 1.3	1.75 2.0 2.5	800 890 †	0.5,1.0	.015 .013 ↓	-4-17 -4-0 0-12 -4-20	•
76 77 78	-BICIWIVITO5SIF1I1	$0.3\\0.95$		2700 1160	0.5,1.0	.058	-4-24 0 -4-20	Yaw
79 80 80 .22 85 86 87	-BlClWlVlT05S0FlI1	1.3 1.05 1.05 0.3 0.95 1.3	2.0 2.5 1.75 2,5	1110 1130 900 2760 800 1100		.017 .02 .058 .02 .017	-4-24 -4-17 17 -4-24 -4-17 -4-10	; ; ; ;
93 94 114 115 119	-B1C1W2V1T05S1F1I1	1.05 0.3 0.6 0.95	2.0 2.5 2.5 1.7	885 2730 1500 800	0.5,1.0,1.5 1.0,1.5 1.5	.02 .13 .067	0-20 -4-15 0-20 -4-24 0-24	Roll
120 123 124	-B1C1W2V1T05S0F111	1.30 0.6 0.95	2.5 1.0 1.75	1100 600 810		.034 .067 .044	0-24 0-15 0-15	•

^{*}Run 46 is additional M = 0.95 data and should be included with Runs $32 \longrightarrow 41$

TABLE 3. ESTIMATED UNCENTAINTIES
a. Dasic Measurements

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10 10 10 10 10 10 10 10			STRAD	1	TE PSTIMA	TED KEASUR	EMENT					
100 100		Precia	sion Index (S)		ig	38	Uncer ±(B +	tainty , t953)		0 000		Method of
### 10.045 + 0.15) 30 ±(0.115 + 1) ±(0.25 + 1.3) 0 to 1300 Datasetrics Datasetrics Property P	Parameter Designation	Percent 20 Reading	Unit of Measure-	Degree of mobesti	i	Measure	Reseast of Percent	lo linu Messure Insm		Measuring Device	Recording Device	Calibration
## ## ## ## ## ## ## ## ## ## ## ## ##	PT, pata	±(0.04% +	0.15) ±0.7	30	+(0.11% +	+ 1) ±2.9	±(0.2% +	1.3) ±4.3	0 to 1500 1500 to 4000		Datametrics Elec- tronic Manometer C-1018	In-place calibration with a precision pressure standard
10.0142 + 0.004) 7 ±0.029 ±(0.035 + 0.038) -8 to 27 Cliffun Procession These Wodel C-5280 Cliffun Procession Digital Indicator CG-10-A5-1 SYNCHRO CG	TT, deg &		1.01	Ф		±0.55		±0.77	410 to 610		Newport Model 2600KF Digital Thermometer	Voltage standard substitution using a stirred ice bath thermocouple
0.052 2 0 0.0-96 0 to 10 Eldurado Freq. FOBCARS Converter Eddel 1602 1602	ALPHA, deg	±(0.014%	+ 0.004)	7			±(0.03% +	0.038)	-8 to 27		Theta Wodel C-5280 Digital Indicator	
•	FREQUENCY, HE	2000		rı .		0	96000		0 to 10	Eldurado Freq. Converter Nodel 1602	FOBCARS	Quency Standard
	·					_		,	•			

TABLE 3. Continued
b. Basic Dynamic Messurements - Pitch/Yaw Balance Assembly

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	Ne se		Control of the control	Sui Dept of the se									
		Type of Recording Device	Ported Open Classon	Control and Readout System (FOBCARS)									
		Type of Messuring Device	Ronded Strain Case						•	•.			
		Range	0.4-1.5	,	0.41.5	0-120	0-42	0.4-0	0140	720	0-4-50	\$7. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.	-
	Uncertainty ±(8 + tg5S)	Valt of September	2.37×10-4	7.00×10-3	1.70x10-2	3.78	3.78	9.12x10-1	3.97×10-1	4.40-02	1.98×10-1	8.18-02	
ENENT	Unce +(B	Percent of Resding											
STEADY-STATE ESTIMATED MEASUREMENT	B188 (B)	Volt of Measure-	2.50×10-3	1.00×10-3	3.00×10-3	0	0	-1.08x10-1	-6.30x10-2	-5.50-03	1.375-02	-2.83-03	
ATE ESTIM	Ø	Jorcent To Saibasa											_
77-57		Degree of Freedom	× 30	> 30	> 30	> 30	> 30	> 30	> 30	> 30	۸ 30	> 30	
STEAL	sion Index (S)	to sinu -erussell -pres	1.06×10-2	3.00×10-3	7.00×10-3	1.89	1.89	5.10x10-1 > 30	2.30x10-1 > 30	1.92-02	1.06×10 ⁻¹	4 .23-02	
	Precision (S)	Percent ot Resolng							,				
		Parameter Designation	POS, deg	In-Phase Torque,	Out-of-Phase Torque,	In-Phase Sting Moment, ft-1b	Out-of-Phase Sting	Normal Force, 1b (Static) (Dynamic)	Side Force, 1b (Static) (Dynamic)	Rulling Noment, ft-15 (Static) (Dynamic)	Pitching Moment, ft-lb (Static) (Uynamic)	Yawing Moment ++-16 (Static) (Dynamic)	

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TABLE 3. Continued C. Basic Dynamic Mensurements - Roll Balance

		STEAL	0Y-ST	ATE ESTIM	STEADY-STATE ESTIMATED MEASUREMENT	EMENT						
	Preci	Precision Index (S)			Bias (B)	Uncer ±(B +	Uncertainty ±(B + tg5S)				, Method of	
Parameter Degignation	Percent of Reading	To tinU -Sesure- fines	lo asigsQ mobsoil	Percent of Reading	lo tinu. -Stuzzsk jasm	Percent to gaibsea	to tinut sautesell finess	64 64 64	Type of Messuring Device	Recording Device	System	
POS, deg		600.0	1~		0.002		0.020	0.5+2.0	Ronded Strain Gares	SONOG		
In Phase Torque, ft-1b	0.04	3.4×10-4	×30 ×30	0.02	1.7×10-3	0.1	63	0-2.3		eu para	Mario Condition	
Out-of-Phase Torque, ft-1b	9.0	3.4×10-4	>30 >30	0.02	1.7×10-3	0.1	2.3x10-3	0-12.3				
Dynamic and Static Forward Normal Porce, 100.08	80.0d	7.0x10-2	88	0.022	0.35	0.18	0.5	300-1500	•			
Dynamic and Static Aft Normal Force, 1b	90.08	7.0x10-Z		0.022	0.35	0.18	5.0	0-+300 300-+1500				
Dynamic and Static Forward Side Force, 1b	0.14	1.1x10 ⁻²	8,8	0.01	5.5x10-2	0.28	80.0	0-128				
Dynamic and Static	0.14	1.1x10-2	8 8 8	0.01	5.5x10-2	0.28	80.0	0-+28 28-+200			·	
Thomson, J. W. and Abernethy, R. B.				n wordpow								
						***	0 mm me m	orenentu.	AEDC-TK-73-5 (AD 75)	of the control of the	1	

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TABLE 3. Continued d. Calculated Parameters

		STEAD	Y-STA	TE ESTIMA	STEADY-STATE ESTIMATED MEASUREMENT*	EMENT*				
	Prect	Precision Index (S)		8	Blas (B)	2 B	Uncertainty ±(B + t95S)			
Parameter Designation	Percent of Reading	Unit of Measure- ment	Degree of	Percent of Reading	Unit of Measure- ment	Percent to Reading	Unit of Measure Measure	Parameter	*	×10-4
Jsd' d		0.71 0.71 0.63			0.0107 0.0107		နာ နာ လ င လဲ လဲ ကဲ င	2722 2594 1162	0000	64 64 64 64 64 64 64 64 64 64 64 64 64 6
		00000					1 0 0 0 0 0 0 1 0 0 4 0 -	#	0 0 0 1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	- 4 - 4 4 4 4 5 - 4 - 5 - 4 - 5 - 4 5 - 4 - 5 - 4 - 5 - 4
×		0.0009 0.0009 0.0013 0.0009 0.0009			0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0		000-00-00 0000000000000000000000000000
Y,ft/sec		0 0007 0 98 1 01 1 01 0 05 0 05 0 05 0 05 0 05 0 05			0 0 0 4 4 6 0 0 0 0 0 0 0 0 0 0 0 0 0 0		6 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1.30 346 346 652 649 984 980 1069	00000 8.6.000 8.0000 8.0000 8.0000	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
RE×10 ⁻⁶ , ft ⁻¹		0.007 0.003 0.002 0.002 0.001 0.001 0.001		-	0.028 0.030 0.012 0.006 0.006 0.005 0.005 0.005		0.042 0.042 0.013 0.003 0.003 0.003 0.003	25 25 25 25 25 25 25 25 25 25 25 25 25 2	0.0000000000000000000000000000000000000	
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Abernethy, R. B. et al	. and Thompson,	Dson. J. W	"Har	ndbook Un	"Handbook Uncertainty in Gas Turbine Measurements."	in Gag Tur	bine Measu	rements.:		

Abernethy, R. B. et al. and Thompson, J. W. "Handbook Uncertainty AEDC-TR-73-5 (AD 755356), February 1973.

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TABLE 3. Continued d. Calculated Parameters

		STEAD	Y-STA7	TE ESTIMA	STEADY-STATE ESTIMATED MEASUREMENT	SMENT				
	Precision (S)	!		ă Č	Bias (B)	Uncer ±(B 4	Uncertminty ±(B + t95S)			
Parameter Designation	Percent of Reading	Unit of Measure- ment	Degree of	Percent of Reading	Unit of Measure- ment	Percent of Reading	to tinU exusseM frem	Parameter	×	RE × 10-6
Q, ps f		0 0 96 0 0 96 0 0 44 0 0 37 0 0 35 0 25			3.92 2.92 2.90 1.86 1.77 1.55 1.55		5 8 8 3 8 5 8 8 3 8 5 8 8 3 8 5 8 8 3 8 3	172 163 293 116 116 284 435 342 473	0.3 0.6 0.95 0.95 1.05 1.05	22212122 22222222222
P/Y CLM-A		0.054 0.023 0.020			0.045 0.018 -0.016		0.153 0.064 0.024	0.400 -0.236 -0.751	0.3 1.30	2.5
P/Y CLM-AD		0.098 0.157 0.149			-0.097 -0.068 -0.072		0.099 0.246 0.226	-5.794 -10.108 -7.855	0.3	
P/Y CLM		0.003 1.200-03 1.100-03			000		88	0.099 0.039 -0.075	0.3	··
CN-A		0.850 0.347 0.299			000		1.700 0.693 0.599	3.457 4.318 5.262	0.3	
CN-AD	•	20.340 22.221 26.477			000		40.680 44.442 52.954	9.977 -10.745 -55.559	0.3 0.95 1.3	
V-KI2		0.08 0.060 0.050			0.04 0.032 0.03		0.2 0.152 0.13	0.257 -0.251 -0.838	0.3 0.95 1.3	
CLK-AD	•	2.737 3.820 1.416			-2.700 -3.66 0.037		2.770 3.980 2.87	-2.847 -5.138 -4.507	0.3 0.95 1.3	·
CLN-A		4 .327-03 3 .976-03 3 .227-03			9.347-03 1.752-03 1.458-03		0.018 9.704-03 7.912-03	0.027 · 0.015 8.119-03	0.95	
כניא-AD		0.225 0.255 0.263			0.106 0.119 0.123		0.556 0.629 0.649	-0.027 0.059 -0.190	0.3 0.95 1.3	•
Shornethy, P. R. at al	and Thomoson.	OSon. J. W	-Han	dbook Un	"Handbook Uncertainty in Gas Turbine Measurements."	n Gas Tur	bine Measu	rements."		-

Abernetby, R. B. et al. and Thompson, J. W. "Handbook Uncertainty in Gas Turbine Measurements." AEDC-TR-73-5 (AD 755356), February 1973.

TABLE 3. Continued d. Calculated Parameters

		STEAD	Y-ST/	TE ESTIM	STEADY-STATE ESTIMATED MEASUREMENT*	EMENT*				
	Prect	Precision Index (S)		В	Bias (B)	Unce ±(B	Uncertainty ±(B + t958)			
Designation	Percent of Reading	Unit of Measure-	Degree of	Percent of Reading	Unit of Measure- ment	rercent To Reading	lo linU Measure faent	Parameter	*	KR × 10
CLL-A		4.561-03 2.286-03 1.463-03			1.586-03 6.163-04		5.188-03	0.026	0,3	2.5
CIT,-AD		0.112 0.127 0.131	i		0.036		0.260		0.3	
P/Y CLN-B		5.825-03 2.686-03 2.768-03			5.042-03 1.876-03		7.248-03	0.105	0.3	
P/T CLN-BD		1.634-02			-7.695-03 -5.731-03		0.021	-0.418 -0.669	0.3	
P/Y CLN		2.800-04 1.141-04 9.847-04			0 0		5.600-04 2.281-04	-6.644-04 2.643-04	0.3	
CY-B		0.080			000		0.160	-4.455-04 -0.959 -1.251	0.3	
CY-BD .		2.320 2.669 2.957			000		4.630 5.339 5.913	-1.181 -1.146 -1.391	0.3	
CLN-B		0.031 0.012 9.349-03			0.022 4.536-03 8.441-03		0.084 0.029 0.27	0.101 0.176 0.253	0.3	
CLN-BD		0.134 0.100 0.067			0.125 0.076 0.042		0.393 0.276 0.176	-0.554 -0.802 -0.633	0.3	
CIN-B		0.145 0.057 0.050			0.057 0.011 0.019		0.347 0.125 0.119	-0.036 0.046 0.022	0.3	
								:		

Abernetby, R. B. et al. and Thompson, J. W. "Handbook Uncertainty in Gas Turbine Measurements." AEDC-TR-73-5 (AD 755358), February 1973. .

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TABLE 3. Concluded b. Calculated Parameters

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		STEAL	Y-STA	TE ESTIM	STEADY-STATE ESTIMATED MEASUREMENT*	EMENT				
	Preci	Precision Index (S)		B	Bias (B)	Uncer ±(B 4	Uncertainty ±(B + t95S)			
Parameter Designation	Percent of Reading	lo jinU -sauzesM -angenj	to estged mobest3	Percent of Reading	to tinU -910269M Juba	Percent of Reading	lo iinU Sessive Jusa	Parasoter	×	788 × 10 *
ספ-איזס		2.539 2.680 2.813	30		0.990 0.195 1.097		6.070 5.555 6.723	0.321 -0.341 2.423	0.0 26.0 26.0	2.5
CLL-B (YAW)		8.272-03 5.623-03 2.076-03			2.774-03 9.240-04 6.738-04		0.019	-0.063 -0.162 -0.119	6.0 6.05	
CIT-8D		0.227			0.073		0.531 0.211 0.587	0.299	0.95	
(נורב) פרדב		3.1x10-3 1.8x10-3 1.1x10-3			3.0×10 ⁻³ 1.7×10 ⁻³ 1.0×10 ⁻³		9.2×10-3 5.3×10-3	, , , ,	3 0.3	2.5
כנדי-580		4.6x10-3 7.4x10-3 6.3x10-3			6.7x10-2 1.1x10-2 8.9x10-3		1.6×10-2 2.7×10-2 2.1×10-2	-2.590×10- -3.382×10- -3.347×10-	0.3	2.5
CLN-PBD		7.0x10-3 1.2x10-2 9.7x10-3			7.1x10-2 0.12 9.0x10-2		.9.0x10-2 .0.14 0.11	-2.4×10-2 5.176×10-2 4.126×10-2		2.5
су Рво		0.02 2.1x10-2 2.2x10-2			0.28 0.24 0.17		0.32		0.3	2.5
CN .							0.022 6.221-03 3.915-03	0.600 0.758 0.656	0.3	?
CY		•		•	•		0.029 1.219-03 1.053-03	4.14-04 5.850-04 2.847-03	0.3	
TIO		1			•		9.760-04	-4.650-04 -1.200-05 6.370-04	0.3	-
כניא		ı			,		6.000-03 2.100-03 1.814-03	0.100	0.3 0.95 1.3	
כדיא		:					4.140-04 1.740-04 1.500-04	5.600-05 1.430-04 -6.550-04	0.3	->
Abernethy, R. B. et al. and Thompson, J. W. "Handbook Uncertainty in Gas Turbine Measurements."	and Thom	pson, J. W	Ħ.	ndbook Un	certainty ;	in Gas Turk	oine Measu	rements."		

Abernethy, R. B. et al. and Thompson, J. W. "Handb AEDC-TR-73-8 (AD 755356), February 1973.

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APPENDIX III

SAMPLE OF TABULATED AND PLOTTED DATA

1	5.3110E=02 5.3110E=02 5.3206E=02 9.2636E=02 9.2636E=02	
TRANSONIC	-2.78335-01 -2.78335-01 -2.6935-01 -4.04315-01 -4.04315-01	
	-1.6145E+00 -2.5145E+00 -2.5147E=00 -2.5147E=01 -2.5147E=01 -2.5147E=01 -4.5147E=01 -4.5147E=01 -4.5147E=01 -4.5147E=01	
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16 SIABILITY	2012000 0000000000000000000000000000000	tic Data h Tabulate
AEDC DYNAHIG	CX 332E-03 360E-03 97E-03 97E-03 960E-03 97E-03 97E-03	a. Sta 1. Pitcl
	5.6105E-02 = 2.58 5.6205E-02 = 2.58 5.6205E-02 = 2.65 9.7711E-02 = 2.20 9.7510E-02 = 2.20	Sample
PANY	-3.4708E+02 5. -3.4701E+02 5. -3.8724E+01 9. -3.8706E+01 9.	
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1.040 2.00 0.51 0.995 47.19 0.0138 2.6554E-0221,4035E-011,1325E-012-12. 1.042 2.00 -3.15 0.804 46.69 0.0137-3.0595E-03-7.995E-02-6.331E-03 1.043 2.00 -3.35 0.979 46.69 0.0136-2.9095E-03-9.1335E-02 5.035E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9097E-03-1,1424E-02 5.0009F-03-1,1424E-02 5.0009F-03-1,1424E-03 5.035E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9097E-03-1,1424E-02 5.035E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9097E-03 1.044 2.00 -3.35 0.999 46.69 0.0136-2.909 46.69 0.0136-2.0097E-03 1.044 2.00 -3.35 0.999 46.69 0	1.050 2.00 0:51	12-1,4452E-01 1,2046E-02
1.044 2.00 -3.35 0.979 46.69 0.0137-2.9096E-03-9.1333E-02 5.6992E-03 1.044 2.00 -3.35 0.979 46.69 0.0137-2.9097E-03-1.1424E-01 4.0559E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9037E-93-1.1424E-01 4.0559E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9037E-93-1.1424E-01 4.0559E-03 1.044 2.00 -3.35 0.979 46.69 0.0136-2.9037E-93-1.1424E-01 4.0559E-03 1.044 2.00 -3.35 0.039 2.03 2.03 2.03 2.03 2.03 2.03 2.03 2.03	1.049 2.00 0.51	12-1,4036E-01 1,3397E-02-
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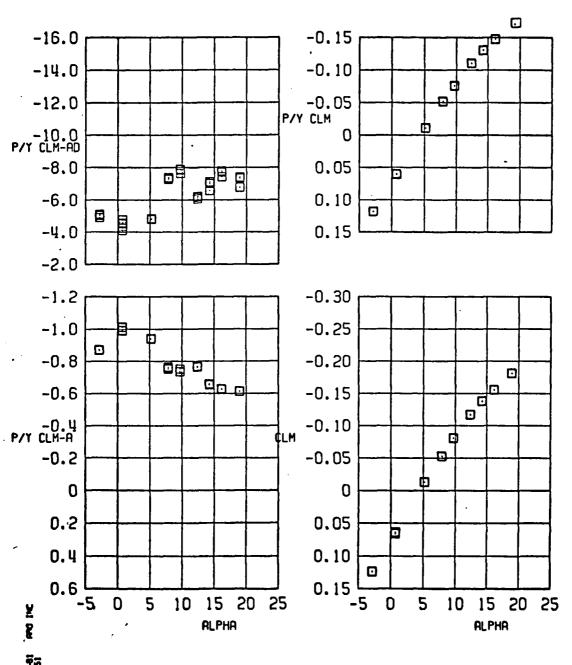
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1.579 1.07 5.07 1.504 51.31 0.0679-6, 81498-03-4, 4498-011, 748-02-6, 1484-11, 1492 1.03 1.03 1.03 1.03 1.03 1.03 1.03 1.03	0,667 1,02 5,01 1,504 53,38	06-03-4.8438-01 6.0698E-02-1.	
0.598 1.02 10.07 1.497 33.45 0.06672-2, 61464-032-2, 00557-011 2, 424-612 2,	0.500 1.02 5.02 1.504 53 38	4F=03=4,8403F=01 7,555CF=02 4	
1.02 15.10 1.491 53.45 0.0667-2.63446-07-2.73778-01 1.04548-07-2.01.594 1.02 15.10 1.491 53.45 0.0655-2.0376-07-2.01.758-01 3.00058-07-2.01.594 1.02 15.10 1.494 53.29 0.0677-2.55748-07-2.0310-2.01.595-07-2.01.596-07-2.01.5	0.548 1.02 10.07 1.494 53.45	XX. = 0.3 = 7, C1, V2. = 0.1 = 1, C1, X.Y. = 0.7, Y. = 0.7, Y. = 0.3, Y.E. = 0.4, Y.E. = 0	
0.594 1.02 15.10 1.492 51.84 0.0665-5.9549-03-2.0410F-01-2.87075-6.7 10.05 1.00 1.00 1.00 1.00 1.00 1.00 1.0	3.431 1.02 15.10 1.491 53.45	6F-42-2-2387F-44 1.4450F-01-4	
0.504 1.03 7.54 1.497 51.29 0.677-5.04540-03-7.0410-01-2.R202E-67 10.504 1.00 7.55 1.407 51.29 0.6677-7.7447-03-1.9104-01-5.4347-07-07 0.501 1.03 5.02 1.507 53.29 0.6677-7.7447-03-1.9104-01-5.4347-07-07 0.501 1.03 5.02 1.507 53.29 0.6677-7.7447-03-1.0157-01-5.4347-07-07 0.501 1.03 2.48 1.507 53.29 0.6677-7.4747-03-1.0157-01-8.71040-07 0.501 1.02 2.47 1.504 53.29 0.6677-4.14777-1.0157-01-8.71040-07 0.501 1.02 4.00 1.507 53.29 0.6677-4.14777-1.0157-01-8.71040-07 0.501 1.03 15.10 1.401 53.78 0.6672-2.5177-01-3.34140-01-2.4117-07 0.501 1.03 15.10 1.487 53.78 0.6672-2.5477-02-1.7487-01 1.5076-02 0.501 1.03 15.10 1.487 53.78 0.6672-2.5477-02-1.44037-01 1.5076-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.56477-02-2.07467-01 1.3078-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.56477-02-2.07467-01 1.3177-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.56477-02-2.07467-01 1.3177-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.56477-02-2.07467-01 1.3177-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.87477-02-2.07467-01 1.3177-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.87477-02-2.07467-01 1.3177-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.87477-02-2.07467-01 1.3177-02 0.501	0.598 1.02 15.10 1.492 53.84	4F-02-7,1175F-01 3,0005F-02-1,	
0.501 1.03 5.02 1.502 51.29 0.0677-7.744Pr-01-4.7043F-01-5.5438-01	9 0,001 1,03 7,54 1,497 53,29 0 0 500 1 00 1 55 1 400 53 20	4F=63+2,0410F+01+2,8202E+62-1,	
0.601 1.03 2.48 1.507 53.29 6.0676-4.41677-03-1.00521-01-4.41377-01-2.06.00 1.03 2.48 1.507 53.29 6.0676-4.41677-03-1.00521-01-4.74617-02 0.599 1.02 4.00 1.502 53.29 0.0677-6.14.7678-01-2.06698-01-2.02 4.00 1.502 53.29 0.0677-6.75165-01-3.4657-01-3.4658-01-2.02 0.500 1.02 4.00 1.502 53.39 0.0677-6.75165-01-3.4658-01-2.41171-02-0.500 1.03 1.506 53.36 0.0677-7.26517-01-3.34147-01-4.1747-02-0.501 1.03 15.10 1.491 53.78 0.0672-2.54178-02-1.4103-01-1.5076-02-0.501 1.03 15.10 1.487 53.78 0.0682-2.56478-02-2.07466-01 3.03332-02-02-02-03-03-03-03-03-03-03-03-03-03-03-03-03-	1 0 hou 1 02 5 02 1 502 5 1 50	7F #0341	
0.501 1.03 2.48 1.507 53.29 0.6678-4.7678E-03-3.06521-01-8.7451F-02 0.509 1.02 2.47 1.508 53.29 0.6678-4.7678E-03-2.0660F-01-1.5060E-02 0.509 1.02 2.47 1.508 53.29 0.6678-4.7678E-03-2.0660F-01-1.5060E-02 0.5001 1.02 4.00 1.501 53.29 0.6677-6.7516E-01-3.46451-01-2.8131E-02-00.5001 1.03 6.03 1.506 53.36 0.6677-7.2651E-01-3.3434-01-4.7434-02 0.501 1.03 15.10 1.486 53.78 0.6672-2.56432E-03-3.3434-01 1.5806E-02 0.501 1.03 15.10 1.487 53.78 0.6682-2.56432E-02-2.1731E-01 1.5816E-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.56432E-02-2.1731E-01 1.5816E-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.8422E-02-2.0746E-01 3.0333E-02 0.501 1.03 15.10 1.487 53.79 0.6682-2.8427E-02-2.0746F-01 3.0333E-02 0.501 1.00 1.00 1.00 1.00 1.00 1.00 1.0	2 0.601 1.03 5.02 1.502 53.29	FF 03-4 H332F 01-4 D005-02 1	•
0.509 1.02 2.47 1.504 53.24 0.0678-1.7678-03-2.0669-01-1.50608-02 0.509 1.02 4.00 1.505 53.29 0.0678-6.34678-01-1.48859-01-1.70718-02-05.001 1.03 4.00 1.501 53.29 0.0678-7.25378-03-3.3448-01-2.41748-02-05.001 1.03 15.10 1.401 53.74 0.0672-7.25378-03-3.3448-01-2.41748-02-02.561 1.03 15.10 1.401 53.74 0.0672-7.5618-02-1.4038-01 1.50268-02-02.561 1.03 15.10 1.407 53.74 0.0682-2.56178-02-2.07468-01 3.0338-02-02.561 1.03 15.10 1.407 53.74 0.0682-2.56178-02-2.07468-01 3.0338-02-02.561 1.03 15.10 1.407 53.79 0.0682-2.8428-02-2.02688-01-1.31378-02-02.5688-01-1.5688-02-02.5688-01-1.31378-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.5688-01-1.5688-02-02.	3 0.601 1.03 2.48 1.507 53.29	7F-03-1,00521-01-8,7401F-02 5	
0,600 1.02 4.00 1.501 53.79 0,0677-6,7516-01-1,4454F-01-4,7111-02-6,600 1.02 6.03 1,504 53.36 0,0677-7,2537E-03-3,3414F-01-4,4114F-02-6,601 1.03 15.10 1.481 53.36 0,0677-7,2651F-03-1,2629-01-4,414FE-02-1,0501 1.03 15.10 1.481 53.78 0,0682-2,5647F-02-2,1174F-01 1.5810E-02-0,0501 1.03 15.10 1.487 53.78 0,0682-2,5647F-02-2,0746F-01 3,033E-02-02-03-03-1,0315-10 1.487 53.79 0,0682-2,8242F-02-2,0268F-01-1,3137E-02-02-03-03-03-03-03-03-03-03-03-03-03-03-03-	4 0.509 1.07 2.47 1.504 53.29	PE-03-2 0660F-01-1 5060E-02 4	
0.500 1.02 6.03 1.504 51.34 0.0677-7.2651F-03-1.2629-01-4.1743F-0.2 0.501 1.03 6.03 1.504 53.34 0.0677-7.2651F-03-1.2629-01-4.4419F-0.2 0.501 1.03 15.10 1.484 53.74 0.0682-2.5647F-02-2.173F-01 1.5026-02 0.501 1.03 15.10 1.487 53.78 0.0682-2.5642F-02-2.0746F-01 3.0333F-02 0.501 1.03 15.10 1.487 53.79 0.0682-2.8427F-02-2.0268F-01-1.3137F-02 0.501 1.03 15.10 1.487 53.79 0.0682-2.8727F-02-2.0268F-01-1.3137F-02 0.501 1.03 15.10 1.487 53.79 0.0682-2.828F-02-2.0268F-01-1.3137F-02 0.501 0.	\$5,550 CO. 0 00.4 CO. 1 00.0 CO. 0 00.0 CO.	/E-04+1,4%5%F-01+8,7%7%F-07-3 68-69-1	
0.601 1.03 6.03 1.506 53.36 0.0677-7.2651F-03-1.2629-01-4.4419F-02 30.501 1.03 15.10 1.491 53.78 0.0682-2.5617F-02-1.4403F-01 1.5026E-02 30.599 1.02 15.10 1.487 53.78 0.0682-2.5617F-02-2.0746F-01 3.0338E-02 0.501 1.03 15.10 1.487 53.79 0.0682-2.872F-02-2.0268F-01-1.3137E-02 5.0268F-01-1.3137E-02 5.0268F-01-	7 0.006 1.02 6.03 1.506 53.36	7E-03-3,3414F-01-4,1745F-02,0	
0.501 1.03 15.10 1.491 53.74 6.6642-2.5617E-02-1.9103F-01 1.5026E-02 2 0.501 1.03 15.10 1.484 53.74 0.6682-2.5617E-02-2.1173F-01 1.5816E-07 1 0.501 1.03 15.10 1.487 53.79 0.6682-2.872F-02-2.0268F-61-1.3137E-02 9 0.501 1.03 15.10 1.487 53.79 0.6682-2.872F-07-2.0268F-61-1.3137E-02 9 b. Dynamic Data Sample 3. Concluded	0,601 1,03 6,03 1,504 53,36	1F-03-3.2629F-01-8.441PE-02 1	
0.559 1.02 15.10 1.487 53.78 0.0642-2.6422F-0.2-2.0746F-0.1 3.03335-0.2 0.00401 1.03 15.10 1.487 53.79 0.0682-2.8242F-0.2-2.0268F-0.1-1.3137F-0.2 0.00682-2.8242F-0.2-2.0268F-0.1-1.3137F-0.2 0.00682	0.001 1.03 15.10 1.491 53.78	-2.5194F=02-1.0403F=01 1.5026E=02 2	
0.501 1.03 15.10 1.487 53.79 0.0682-7.8247F-07-2.0268F-01-1.3137F-02 9	0.500 1.02 15.10 1.460 53.78	2 64225 412-2 1.7445-61 1 34105-07 1	
Dynam e 3.	0.501 1.03 15.10 1.487 53.79	2F-02-2,0268F-01-1,3137F-02 9	
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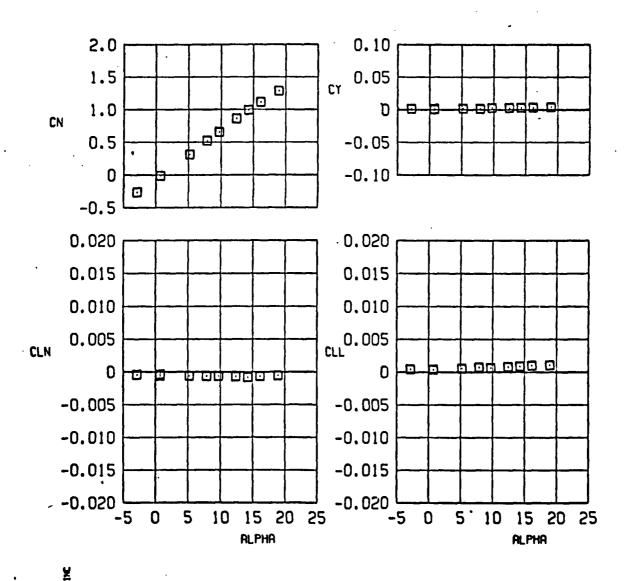
_ SYM CONFIGURATION M REX10-8 RFP RUN
 -B1C1W1V1T05S1F111 1.30 2.50 0.01 45



Sample 4. Pitch Plotted Data

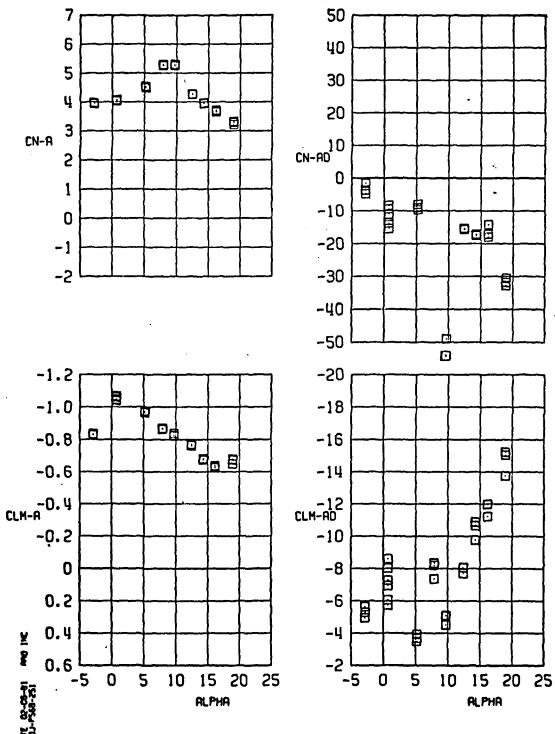
SYM CONFIGURATION M REX10-6 RFP RUN

-B1C1W1V1T05S1F111 1.30 2.50 0.01 45



Sample 4. Continued

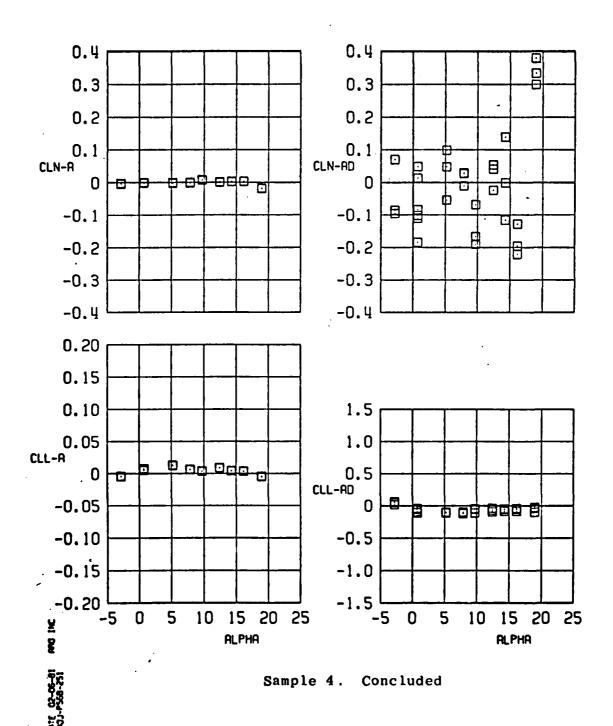
SYM CONFIGURATION M REX10-6 RFP RUN
-B1C1W1V1T05S1F111 1.30 2.50 0.01 45



Sample 4. Continued

 SYM
 CONFIGURATION
 M
 REX10-6
 RFP
 RUN

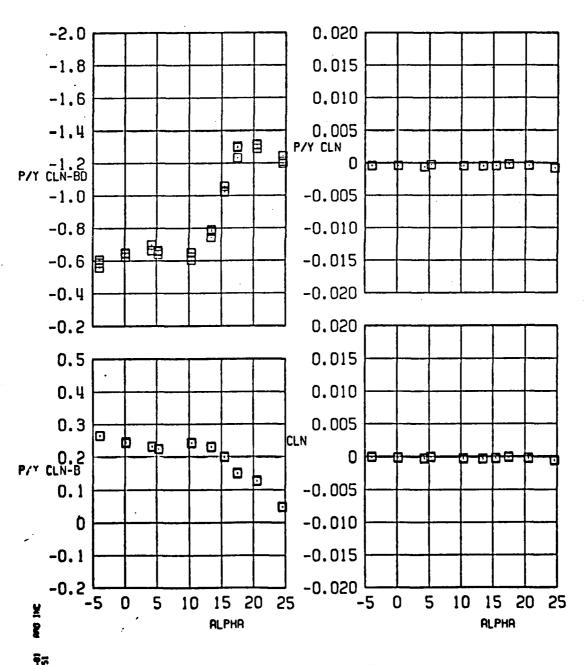
 ID
 FB1C1W1V1T05S1F111
 1.30
 2.50
 0.01
 45



The second secon

SYM CONFIGURATION M REX10-6 RFP RUN

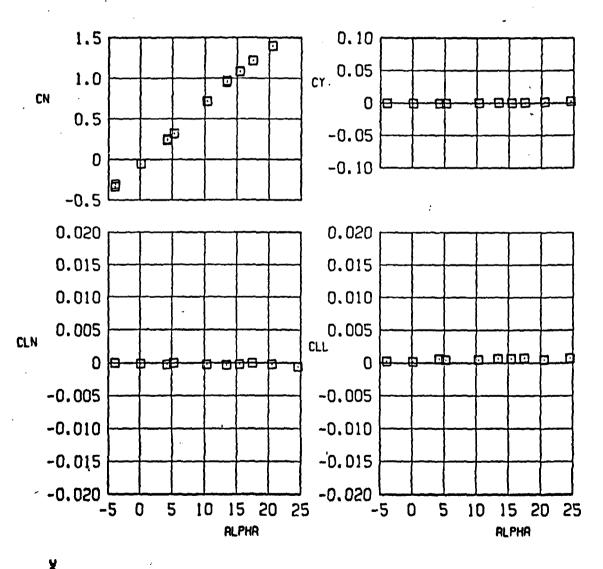
-B1C1W1V1T05S1F111 1.30 2.50 0.02 79



Sample 5. Yaw Plotted Data

 SYM
 CONFIGURATION
 M
 REX10-6
 RFP
 RUN

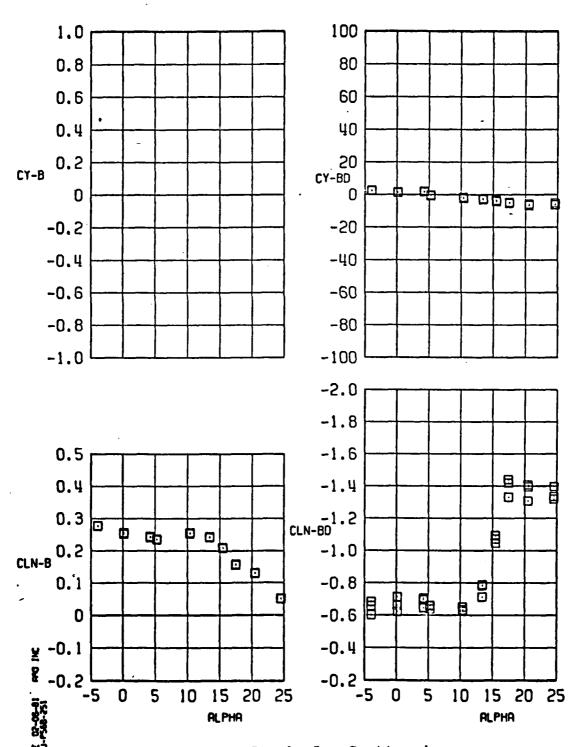
 ID
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 1.30
 2.50
 0.02
 79



Sample 5. Continued

A 16-30-00 111

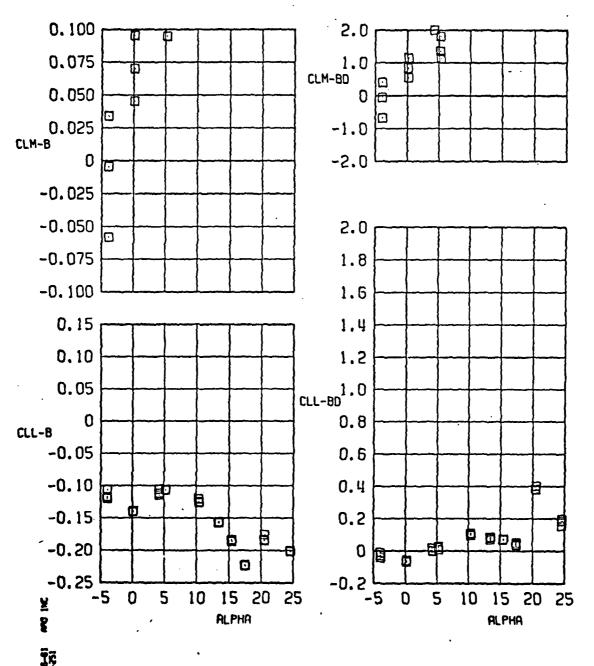
.SYM CONFIGURATION M REX10-6 RFP RUN
-BICIWIVITOSSIFIII 1.30 2.50 0.02 79



Sample 5. Continued

 SYM
 CONFIGURATION
 M
 REX10-6
 RFP
 RUN

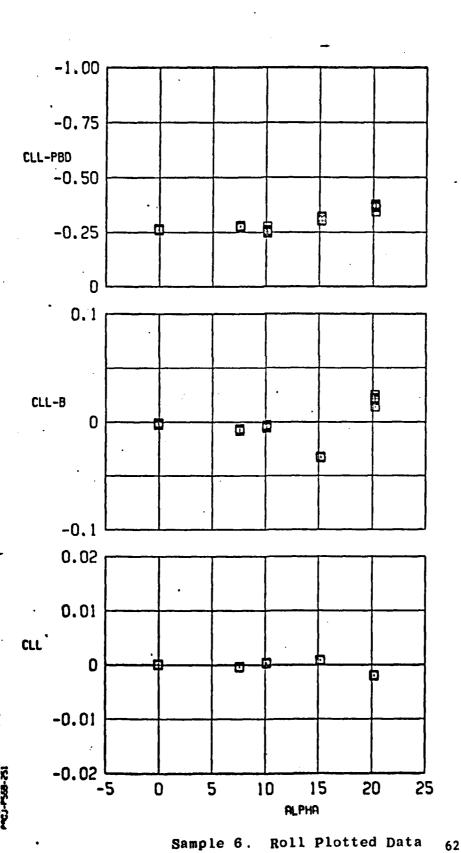
 D
 -B1C1W1V1T05S1F111
 1.30
 2.50
 0.02
 79



Sample 5. Concluded

 SYM
 CONFIGURATION
 M
 REX10⁻⁶
 RFP
 RUN

 □
 -B1C1W2V1T05S1F111
 0.30
 2,49
 0.13
 114



 SYM
 CONFIGURATION
 M
 REX10-6
 RFP
 RUN

 -B1C1W2V1T05S1F111
 0.30
 2.49
 0.13
 114

